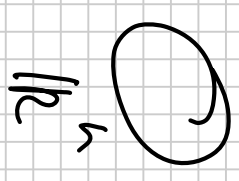
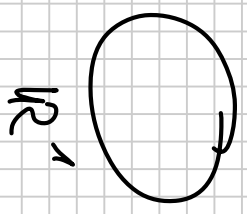


# HM2 M4 GW Blatt 11



Skalarfeld  $\mathbb{R}^n \rightarrow \mathbb{R}$

$\nabla f$ ,  $H_f$

Vektorfeld  $\mathbb{R}^n \rightarrow \mathbb{R}^n$

$$J_f = \begin{pmatrix} \nabla f_1^T \\ \nabla f_2^T \end{pmatrix}$$

i) EV, EW

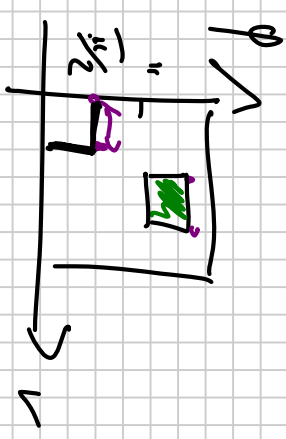
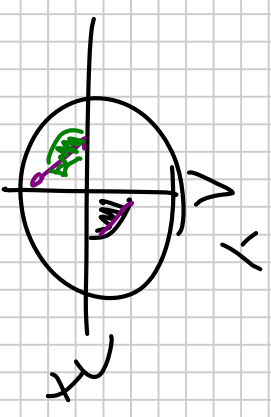
$\rightarrow$  Trafo

Entkoppel

ii) Satz impl Fkt

Reduktion

ad i)

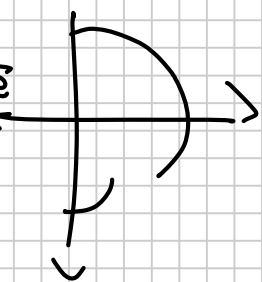
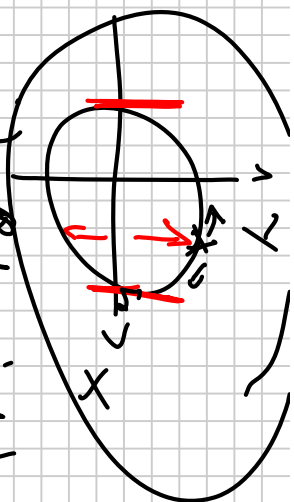
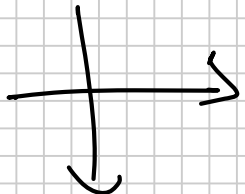


1)

a)

$$x_1 + x_2 - \sin(x_3) = 0$$

$$\exp(x_3) - x_1 - x_2 = 1$$



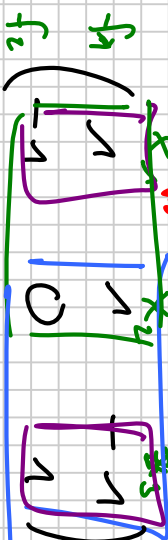
Berechnung

$$\det A = \prod \lambda_i$$

$$\text{Spur } A = \sum a_{ii} = \sum \lambda_i$$

$$J_f = \begin{pmatrix} 1 & 1 & -\cos(x_3) \\ -1 & -3x_2^2 & \exp(x_3) \end{pmatrix}$$

$A \cdot x = ?$   $\rightarrow$  wird nicht



$$J_f(0,0,0) = f_z$$

$$(x_1, x_2)$$

$$\begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix}, \det = 1 \cdot 0 - (-1 \cdot 1) = 1$$

auflöser

$$(x_2, x_3)$$

$$\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}, \det = 1$$

auflöser

$$(x_1, x_3)$$

$$\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}, \det = 0$$

nicht auflösbar

Einsatz Taylor

$$f(x) = f(x_0) + \frac{f'(x_0)}{1!} (x - x_0) + \frac{f''(x_0)}{2!} (x - x_0)^2 + \dots$$

$$\text{Skalar } f(x) = f(x_0) + Df(x_0) \cdot (x - x_0) + \frac{1}{2} D^2 f(x_0) \cdot (x - x_0)^2 + \dots$$

$$\text{Vektor } f(x) = f(x_0) + Df(x_0) \cdot (x - x_0) + \dots$$

$\det J_f \neq 0$

$$-f_y \neq 0$$

$\nabla f$  muss

ii) stetig diff. sein

c) Bei minimalen Punkten

b)  $x_1 + x_2 - \sin x_3 = 0$

$\exp x_1 - x_1^2 + x_2 = 1$

iii)

$J_f = \begin{pmatrix} 1 & 1 & -\cos x_3 \\ -2x_1 + \exp x_1 & 1 & 0 \end{pmatrix}$

$J_f(0,0,0) = \begin{pmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \end{pmatrix}$

$(x_1, x_2)$

$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

$\det = 0$

$\Rightarrow$  nicht auflösbar

$\parallel \vec{0}$

"0 auf der Seite"

i)  $\vec{0}$  erfüllt die Gleichung

ii) die Fkt sind stetig diffbar

was ist f?

$\mathbb{R}^3 \rightarrow \mathbb{R}^2$

$f = \begin{pmatrix} x_1 + x_2 - \sin x_3 \\ \exp x_1 - x_1^2 + x_2 - 1 \end{pmatrix}$

$(x_2, x_3)$

$\begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix}$

$\det = 1$

auflösen

$(x_1, x_3)$

$\begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix}$

$\det = 1$

auflösen

Transformation eines Vektorfeldes

$\vec{v}_{alt}(\vec{x})$  Vektorfeld

$\vec{v}_{neu}(\vec{y}) = T \cdot \vec{v}_{alt}(\vec{x})$

$\vec{v}_{alt}(\phi(\vec{y}))$

Info-Matrix  $T = \phi'(\vec{y})$

$\vec{x} = \phi(\vec{y})$   
alt koordinat neu koordinat

Bewertung

grob  $f: \nabla \cdot f =$

$\left( \frac{1}{\partial x} \frac{\partial}{\partial x} + \frac{1}{\partial y} \frac{\partial}{\partial y} + \frac{1}{\partial z} \frac{\partial}{\partial z} \right) \cdot f =$

$\left( \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} + \frac{\partial f}{\partial z} \right)$

hier Skalarpotential

$\text{div } \vec{v} =$

$\left( \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right)$

$\vec{v} = \nabla \cdot \vec{v} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z}$

$\text{rot } \vec{v} =$

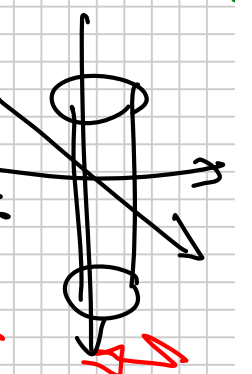
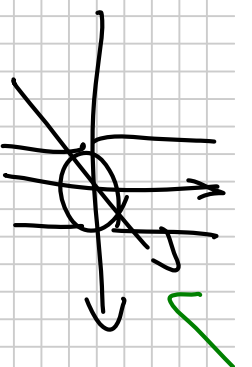
$\nabla \times \vec{v} =$

$\begin{pmatrix} \frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \\ \frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \\ \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \end{pmatrix}$

## Aufgabe 2:

$$\vec{v}_{\text{rot}}(x, y, z) = \frac{1}{\sqrt{x^2 + y^2}}$$

$$\begin{pmatrix} xz \\ yz \\ \sqrt{x^2 + y^2}z \end{pmatrix}$$



$\vec{z}$ -Lind-Koord.:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \phi(r, \varphi, z) = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \\ z \end{pmatrix}$$



$$\vec{v}_{\vec{z}}(\text{Koord.})$$

$$\vec{v}_{\text{rot}} = \frac{1}{\sqrt{x^2 + y^2}} \begin{pmatrix} \cos \varphi & \sin \varphi & 0 \\ -\sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

Einsche

$$\text{rot } \vec{v} =$$

$$= \frac{1}{\sqrt{x^2 + y^2}} \begin{pmatrix} -y \\ x \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} z \\ 0 \\ 1 \end{pmatrix}$$

$$\text{div } \vec{v} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} = \left( \frac{\partial}{\partial x} \frac{xz}{\sqrt{x^2 + y^2}} \right) + \left( \frac{\partial}{\partial y} \frac{yz}{\sqrt{x^2 + y^2}} \right) + \frac{\partial 1}{\partial z} =$$

$$= \left( \frac{z}{\sqrt{x^2+y^2}} + x \cdot \frac{\left(-\frac{1}{2}\right) \cdot 2x \cdot z}{(x^2+y^2)^{3/2}} \right) + \quad + \sigma$$

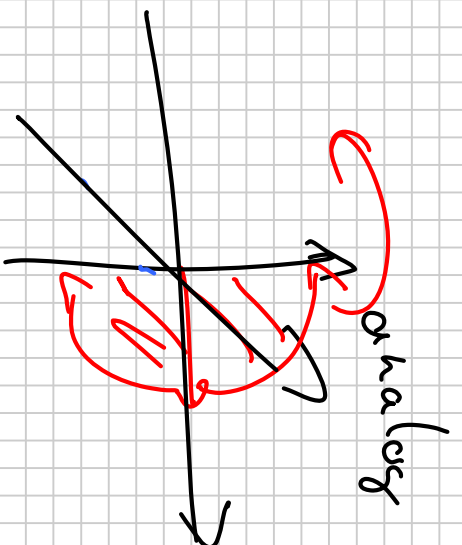
$$= \frac{z(x^2+y^2) - x^2 z}{(x^2+y^2)^{3/2}} + \quad "$$

$$= \frac{y^2 z}{(x^2+y^2)^{3/2}} + \frac{x^2 z}{(x^2+y^2)^{3/2}}$$

$$v_0 + \vec{v}_{2\gamma c} (v, \varphi, z) = \left( \frac{1}{r} \frac{\partial v_1}{\partial \varphi} - \frac{\partial v_2}{\partial z} \right) = \dots = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{div } \vec{v}_{2\gamma c} (v, \varphi, z) = \left[ \frac{1}{r} \frac{\partial (r v_1)}{\partial r} + \frac{1}{r} \frac{\partial v_2}{\partial \varphi} + \frac{\partial v_3}{\partial z} \right] = \dots = \frac{z}{r}$$

Aufgabe 3: Kugelkoordinat

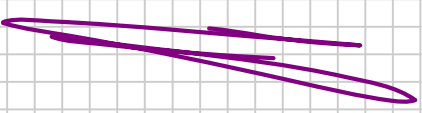
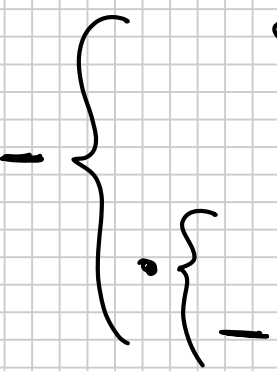
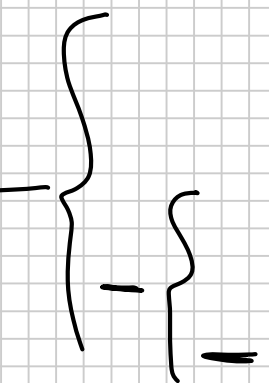


Formeln: rot liegt

div liegt

Aufgabe 4:

$$\text{rot}(\text{rot } \vec{a}) = -\Delta \vec{a} + \text{grad}(\text{div } \vec{a})$$



$$\text{rot } \vec{a} = \begin{pmatrix} \partial_2 a_3 - \partial_3 a_2 \\ \partial_3 a_1 - \partial_1 a_3 \\ \partial_1 a_2 - \partial_2 a_1 \end{pmatrix}$$



für

Ausprägung einer Quadril:

siehe Skript S. 198/199